

EAST SEARCH

4/4/2007

L#	Hits	Search String	Databases
S1	58261	(augmented near2 reality) or (computer near2 vision) or (video near2 processing)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S2	2664	S1 and (camera with captur\$3 with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S3	12	S2 and (track\$3 with movement with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S4	274	S2 and (captur\$3 with image with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S5	5	S2 and (captur\$3 with visual with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S6	1	S2 and (identify\$3 with natural with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S7	15	S2 and (identify\$3 with surface with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S8	496	S2 and (image near2 sequence)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S9	327	S2 and (feature with (position or location))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S10	32	S2 and ((3-dimensional or three-dimensional) with surface with (location or orientation))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S11	2	S2 and (coplanar with feature with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S12	265	S2 and ((flat or (two-dimensional or 2-dimensional)) with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S13	1	S2 and ((irregular near2 body) with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S14	8	S2 and (supplemental near2 image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S15	6	S2 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S16	2	S2 and (compar\$3 with feature with contrast)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S17	0	S2 and (compar\$3 with feature with uniqueness)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S18	8	S2 and (compar\$3 with accuracy with (position or orientation or surface))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S19	13	S2 and (select\$3 with feature with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S20	36	S2 and (measur\$3 with distance with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S21	26	S2 and ((location or orientation) with surface with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S22	10	S2 and (predict\$3 with position with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S23	0	S2 and (search\$3 with feature with zone)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S24	18	S2 and (search\$3 with feature with (range or window))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S25	3	S2 and (surface with (fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S26	45	S2 and ((fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S27	5	S2 and ((fiducial or reference) with marker with (pattern or "square shaped"))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S28	49	S2 and ((surface or camera) with (movement or mov\$3) with environment)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S29	6	S2 and (surface with visual with appearance)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S30	231	S3 or S5 or S6 or S7 or S10 or S11 or S13 or S14 or S15 or S16 or S18 or S19 or S20 or S2	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S31	1066	S4 or S8 or S9 or S12	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S32	157	S30 and S31	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S33	231	S30 or S32	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S34	19	S33 and (S5 or S6 or S7)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S35	18	S33 and S24	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S36	58276	(augmented near2 reality) or (computer near2 vision) or (video near2 processing)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S37	2664	S36 and (camera with captur\$3 with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S38	12	S37 and (track\$3 with movement with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S39	274	S37 and (captur\$3 with image with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S40	5	S37 and (identify\$3 with visual with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S41	1	S37 and (identify\$3 with natural with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB

S42	15	S37 and (identify\$3 with surface with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S43	496	S37 and (image near2 sequence)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S44	327	S37 and (feature with (position or location))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S45	32	S37 and ((3-dimensional or three-dimensional) with surface with (location or orientation))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S46	2	S37 and (coplanar with feature with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S47	265	S37 and ((flat or (two-dimensional or 2-dimensional)) with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S48	1	S37 and ((irregular near2 body) with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S49	8	S37 and (supplemental near2 image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S50	6	S37 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S51	2	S37 and (compar\$3 with feature with contrast)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S52	8	S37 and (compar\$3 with accuracy with (position or orientation or surface))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S53	13	S37 and (select\$3 with feature with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S54	36	S37 and (measur\$3 with distance with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S55	26	S37 and ((location or orientation) with surface with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S56	10	S37 and (predict\$3 with position with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S57	18	S37 and (search\$3 with feature with (range or window))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S58	3	S37 and (surface with (fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S59	45	S37 and ((fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S60	5	S37 and ((fiducial or reference) with marker with (pattern or "square shaped"))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S61	49	S37 and ((surface or camera) with (movement or mov\$3) with environment)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S62	6	S37 and (surface with visual with appearance)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S63	231	S38 or S40 or S41 or S42 or S45 or S46 or S48 or S49 or S50 or S51 or S52 or S53 or S54	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S64	1066	S39 or S43 or S44 or S47	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S65	157	S63 and S64	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
S66	231	S63 or S65	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L1	64145	(augmented near2 reality) or (computer near2 vision) or (video near2 processing)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L2	3164	L1 and (camera with captur\$3 with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L3	14	L2 and (track\$3 with movement with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L4	319	L2 and (captur\$3 with image with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L5	8	L2 and (identify\$3 with visual with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L6	1	L2 and (identify\$3 with natural with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L7	21	L2 and (identify\$3 with surface with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L8	596	L2 and (image near2 sequence)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L9	413	L2 and (feature with (position or location))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L10	38	L2 and ((3-dimensional or three-dimensional) with surface with (location or orientation))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L11	2	L2 and (coplanar with feature with image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L12	303	L2 and ((flat or (two-dimensional or 2-dimensional)) with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
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L14	9	L2 and (supplemental near2 image)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L15	7	L2 and (superimpos\$3 with (3-dimensional or three-dimensional) near2 (view or object))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L16	3	L2 and (compar\$3 with feature with contrast)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L17	9	L2 and (compar\$3 with accuracy with (position or orientation or surface))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L18	21	L2 and (select\$3 with feature with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L19	42	L2 and (measur\$3 with distance with surface)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L20	34	L2 and ((location or orientation) with surface with (size or range))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L21	10	L2 and (predict\$3 with position with feature)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L22	20	L2 and (search\$3 with feature with (range or window))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB

L23	4	L2 and (surface with (fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L24	55	L2 and (fiducial or reference) with marker)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L25	6	L2 and (fiducial or reference) with marker with (pattern or "square shaped")	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L26	62	L2 and (surface or camera) with (movement or mov\$3) with environment)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L27	6	L2 and (surface with visual with appearance)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L28	281	L3 or L5 or L6 or L7 or L10 or L11 or L13 or L14 or L15 or L16 or L17 or L18 or L19 or L20 or	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L29	1268	L4 or L8 or L9 or L12	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L30	192	L28 and L29	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L31	281	L28 or L30	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB
L32	16325	(augmented near2 reality) or (computer near2 vision) or (video near2 processing)	US-PGPUB
L33	1573	32 and (camera with captu\$3 with image)	US-PGPUB
L34	6	33 and (track\$3 with movement with surface)	US-PGPUB
L35	6	33 and (identify\$3 with visual with feature)	US-PGPUB
L36	14	33 and (identify\$3 with surface with feature)	US-PGPUB
L37	21	33 and ((3-diemensional or three-dimensional) with surface with (location or orientation))	US-PGPUB
L38	41	34 or 35 or 36 or 37	US-PGPUB
L39	0	38 and (compar\$3 with feature with contrast)	US-PGPUB
L40	0	38 and (compar\$4 with feature with contrast)	US-PGPUB
L41	0	38 and (compar\$4 with feature with uniqueness)	US-PGPUB
L42	2	38 and (subset with feature)	US-PGPUB
L43	3	38 and (size with feature)	US-PGPUB
L44	0	38 and (search near2 zone)	US-PGPUB
L45	3	38 and (contrast.CLM.)	US-PGPUB
L46	1	38 and (uniqueness.CLM.)	US-PGPUB
L47	1	38 and ("search zones".CLM.)	US-PGPUB
L48	3	45 or 46 or 47	US-PGPUB

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Results of search set S91:

Document Kind	Code	Title	Issue Date	Current OR	Abstract
US	20060153469	A1 Image processing based on ambient air attributes	20060713	382/254	
US	20060152434	A1 Calibrating real and virtual views	20060713	345/8	
US	20060139314	A1 Interactive video display system	20060629	345/156	
US	20060133642	A1 Image recognition facilitation using remotely sourced content	20060622	382/100	
US	20060132467	A1 Method and apparatus for calibrating a camera-based whiteboard scanner	20060622	345/178	
US	20060115157	A1 Image processing device, image device, image processing method	20060601	382/190	
US	20060091215	A1 Two-dimensional code and information processing method	20060504	235/462.1	
US	20060088187	A1 Method and apparatus for situation recognition using optical information	20060427	382/103	
US	20060079324	A1 Image display system, image processing system, and video game system	20060413	463/30	
US	20060073892	A1 Image display system, information processing system, image processing system, and video g	20060406	463/34	
US	20060071946	A1 Information processing method and apparatus	20060406	345/633	
US	20060050386	A1 Catadioptric single camera systems having radial epipolar geometry and methods and means	20060309	359/471	

US 20060036947 A1	User interface controller method and apparatus for a handheld electronic device	20060216 715/722
US 20060022962 A1	Size/scale and orientation determination of a pointer in a camera-based touch system	20060202 345/175
US 20060013441 A1	Image monitoring method, image monitoring apparatus and storage media	20060119 382/103
US 20060013440 A1	Gesture-controlled interfaces for self-service machines and other applications	20060119 382/103
US 20060008268 A1	Three-dimensional image processing apparatus, optical axis adjusting method, and optical a	20060112 396/310
US 20060004280 A1	Placement information estimating method and information processing device	20060105 600/414
US 20050289590 A1	Marketing platform	20051229 725/37
US 20050288078 A1	Game	20051229 463/1
US 20050285878 A1	Mobile platform	20051229 345/633
US 20050284937 A1	Automated dimensional inspection	20051229 235/437
US 20050278098 A1	Vehicular impact reactive system and method	20051215 701/45
US 20050276444 A1	Interactive system and method	20051215 382/103
US 20050272501 A1	Automated game monitoring	20051208 463/29
US 20050264555 A1	Interactive system and method	20051201 345/419
US 20050264433 A1	Image display apparatus, image display method, measurement apparatus, measurement met	20051201 340/937
US 20050257748 A1	Apparatus and methods for the volumetric and dimensional measurement of livestock	20051124 119/51.02
US 20050256391 A1	Information processing method and apparatus for finding position and orientation of targeted li	20051117 600/407
US 20050254726 A1	Methods, systems, and computer program products for imperceptibly embedding structured li	20051117 382/285
US 20050253870 A1	Marker placement information estimating method and information processing device	20051117 345/633
US 20050248729 A1	Selectable projector and imaging modes of display table	20051110 353/71
US 20050248539 A1	Apparatus and method for detecting a pointer relative to a touch surface	20051110 345/173
US 20050234333 A1	Marker detection method and apparatus, and position and orientation estimation method	20051020 600/426
US 20050231713 A1	Imaging semiconductor structures using solid state illumination	20051020 356/237.1
US 20050227217 A1	Template matching on interactive surface	20051013 434/337
US 20050215879 A1	Accuracy evaluation of video-based augmented reality enhanced surgical navigation systems	20050929 600/407
US 20050213807 A1	System and method for excluding extraneous features from inspection operations performed	20050929 382/152
US 20050213790 A1	Methods for using wireless phones having optical capabilities	20050929 382/100
US 20050195383 A1	Method for obtaining information about objects in a vehicular blind spot	20050908 356/4.01
US 20050190972 A1	System and method for position determination	20050901 382/218
US 20050189411 A1	Systems and methods for merchandise checkout	20050901 235/383
US 20050185054 A1	System, method and article of manufacture for tracking a head of a camera-generated image	20050825 348/169
US 20050180623 A1	Method and apparatus for scanning three-dimensional objects	20050818 382/154
US 20050163343 A1	Movable body circumstance monitoring apparatus	20050728 382/103
US 20050162409 A1	Projector and camera arrangement with shared optics and optical marker for use with whitebr	20050728 345/173
US 20050159916 A1	Information processing apparatus, and information processing method	20050721 702/151
US 20050149877 A1	Graphical user interface for 3-D in-vivo imaging	20050707 715/764
US 20050149231 A1	Method and a system for programming an industrial robot	20050707 700/264
US 20050145786 A1	Phantom calibration device for low level light imaging systems	20050707 250/252.1
US 20050128196 A1	System and method for three dimensional modeling	20050616 345/420
US 20050083248 A1	Mobile face capture and image processing system and method	20050421 345/8
US 20050069196 A1	Index identification method and apparatus	20050331 382/154
US 20050069174 A1	Position and orientation estimating method and apparatus	20050331 382/103
US 20050054910 A1	Optical image-based position tracking for magnetic resonance imaging applications	20050310 600/411
US 20050036672 A1	Three-dimensional active vision with glyph address carpet	20050217 382/154
US 20050033142 A1	Method of indexing biological imaging data using a three-dimensional body representation	20050210 600/407
US 20050018058 A1	Method and system for reconstructing 3D interactive walkthroughs of real-world environments	20050127 348/239
US 20050012830 A1	Autonomous camera having exchangeable behaviours	20050120 348/231.99
US 20050008343 A1	Producing video and audio-photos from a static digital image	20050113 386/121

US 20040258314 A1	Region segmentation and characterization systems and methods for augmented reality	20041223 382/224
US 20040258306 A1	Fiducial designs and pose estimation for augmented reality	20041223 382/181
US 20040258152 A1	System and method for using motion vectors for object tracking	20041223 375/240.16
US 20040247193 A1	Method and apparatus for article inspection	20041209 382/243
US 20040240750 A1	Method and system for producing formatted data related to geometric distortions	20041202 382/275
US 20040239756 A1	Method and apparatus for computing error-bounded position and orientation of panoramic camera	20041202 348/36
US 20040223058 A1	Systems and methods for multi-resolution image processing	20041111 348/207.1
US 20040220965 A1	Indexed database structures and methods for searching path-enhanced multimedia	20041104 707/104.1
US 20040218895 A1	Apparatus and method for recording "path-enhanced" multimedia	20041104 386/46
US 20040218099 A1	Systems and methods for multi-stream image processing	20041104 348/571
US 20040212630 A1	Method for automatically tracking objects in augmented reality	20041028 345/633
US 20040196282 A1	Modeling and editing image panoramas	20041007 345/419
US 20040184653 A1	Optical inspection system, illumination apparatus and method for use in imaging specular objects	20040923 382/145
US 20040184648 A1	System and method for shape reconstruction from optical images	20040923 382/141
US 20040184032 A1	Optical inspection system and method for displaying imaged objects in greater than two dimensions	20040923 356/237.3
US 20040184031 A1	Optical inspection system, apparatus and method for reconstructing three-dimensional image	20040923 356/237.1
US 20040161132 A1	Gesture-controlled interfaces for self-service machines and other applications	20040819 382/103
US 20040148057 A1	Vehicular exterior identification and monitoring system-agricultural product distribution	20040729 700/242
US 20040136574 A1	Face image processing apparatus and method	20040715 382/118
US 20040136567 A1	Tracking a surface in a 3-dimensional scene using natural visual features of the surface	20040715 382/103
US 20040135886 A1	Moving image camera for track and range capture	20040715 348/143
US 20040131232 A1	Augmented reality technology	20040708 382/103
US 20040130618 A1	Automated wheel slide detector	20040708 348/61
US 20040126008 A1	Analyte recognition for urinalysis diagnostic system	20040701 382/156
US 20040113818 A1	Image display apparatus, image display method, measurement apparatus, measurement method	20040617 340/995.1
US 20040095318 A1	Size/scale and orientation determination of a pointer in a camera-based touch system	20040520 345/158
US 20040069934 A1	Passive touch-sensitive optical marker	20040415 250/221
US 20040066500 A1	Occupancy detection and measurement system and method	20040408 356/4.01
US 20040052418 A1	Method and apparatus for probabilistic image analysis	20040318 382/209
US 20040032495 A1	Providing multiple synchronized camera views for broadcast from a live venue activity to remote	20040219 348/157
US 20040032407 A1	Method and system for simulating stereographic vision	20040219 345/419
US 20040028258 A1	Fiducial detection system	20040212 382/103
US 20040008259 A1	Optical methods for remotely measuring objects	20040115 348/207.1
US 20040001637 A1	Adaptive generation of Q-table2 for improved image quality	20040101 382/239
US 20030231179 A1	Internet system for virtual telepresence	20031218 345/423
US 20030218688 A1	Method and apparatus for automatically optimizing optical contrast in automated equipment	20031127 348/370
US 20030197867 A1	Video camera-based visibility measurement system	20031023 356/437
US 20030193562 A1	Natural vision-based video surveillance system	20031016 348/148
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L33	1573	32 and (camera with captur\$3 with image)	US-PGPUB
L34	6	33 and (track\$3 with movement with surface)	US-PGPUB
L35	6	33 and (identify\$3 with visual with feature)	US-PGPUB
L36	14	33 and (identify\$3 with surface with feature)	US-PGPUB
L37	21	33 and ((3-diemsional or three-dimensional)) with surface with (location or orientation))	US-PGPUB
L38	41	34 or 35 or 36 or 37	US-PGPUB
L39	0	38 and (compar\$3 with feature with contrast)	US-PGPUB
L40	0	38 and (compar\$4 with feature with contrast)	US-PGPUB
L41	0	38 and (compar\$4 with feature with uniqueness)	US-PGPUB
L42	2	38 and (subset with feature)	US-PGPUB
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